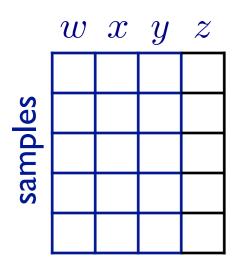
# General Purpose SAT-Solvers for Causal Discovery

Frederick Eberhardt
Caltech

[joint work with Antti Hyttinen and Matti Jarvisalo]

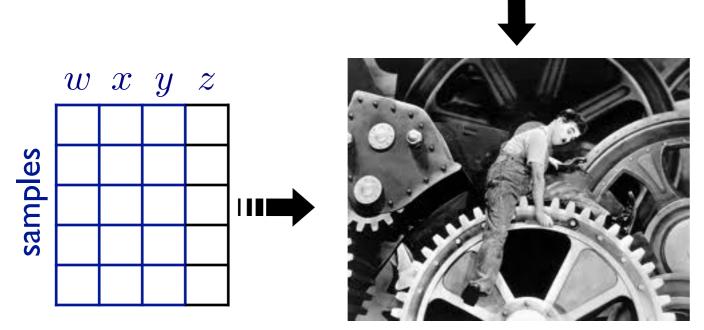
data sample



#### assumptions, e.g.

- causal Markov
- causal faithfulness
- functional form
- etc.

# data sample



inference algorithm

# data sample

# w x y z

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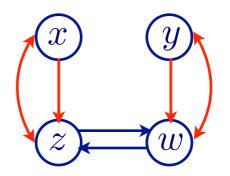


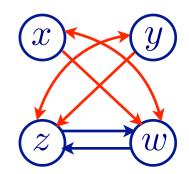


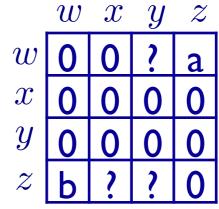
inference algorithm

#### equivalence classes

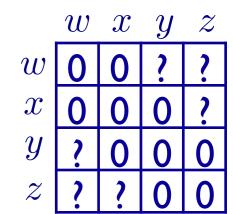
model specifications











confounders

assumption / algorithm

Markov

faithfulness

causal sufficiency

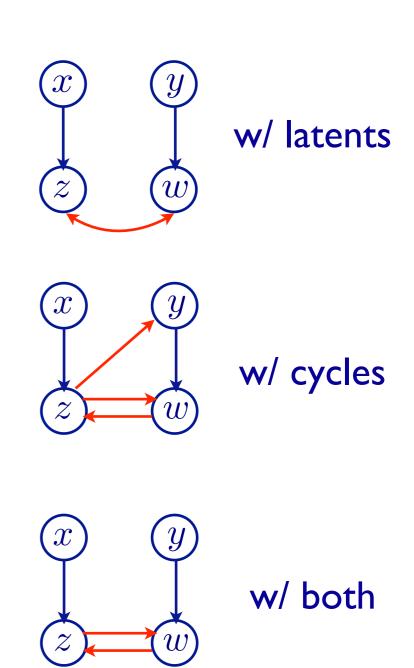
acyclicity

parametric assumption

assumption / algorithm	PC / GES	FCI	CCD	LiNGaM	non-linear additive noise
Markov	✓	✓	<b>√</b>	✓	✓
faithfulness	✓	✓	✓	Х	minimality
causal sufficiency	✓	X	✓	✓	✓
acyclicity	✓	✓	X	✓	√
parametric assumption	X	X	X	linear non- Gaussian	non-linear additive noise

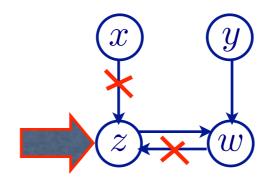
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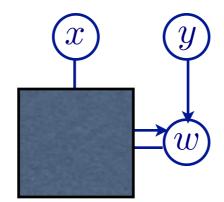


#### Combining Experiment and Observation

#### experiment

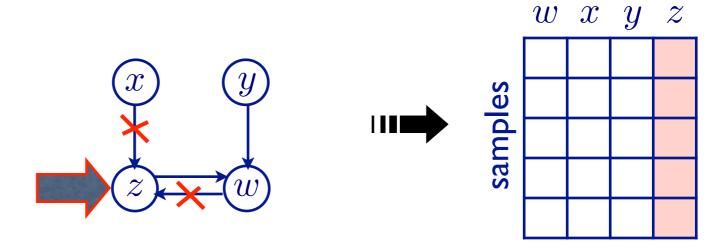


#### observational study

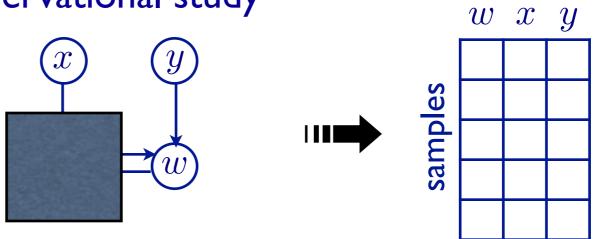


#### Combining Experiment and Observation

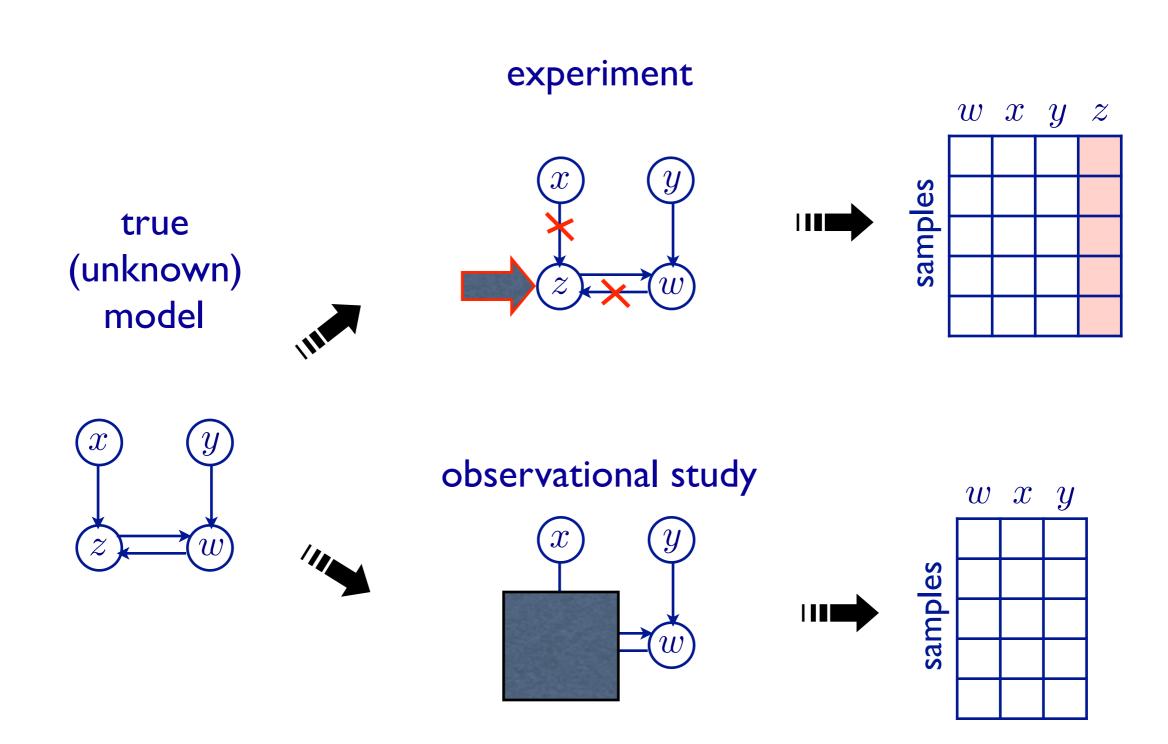
#### experiment

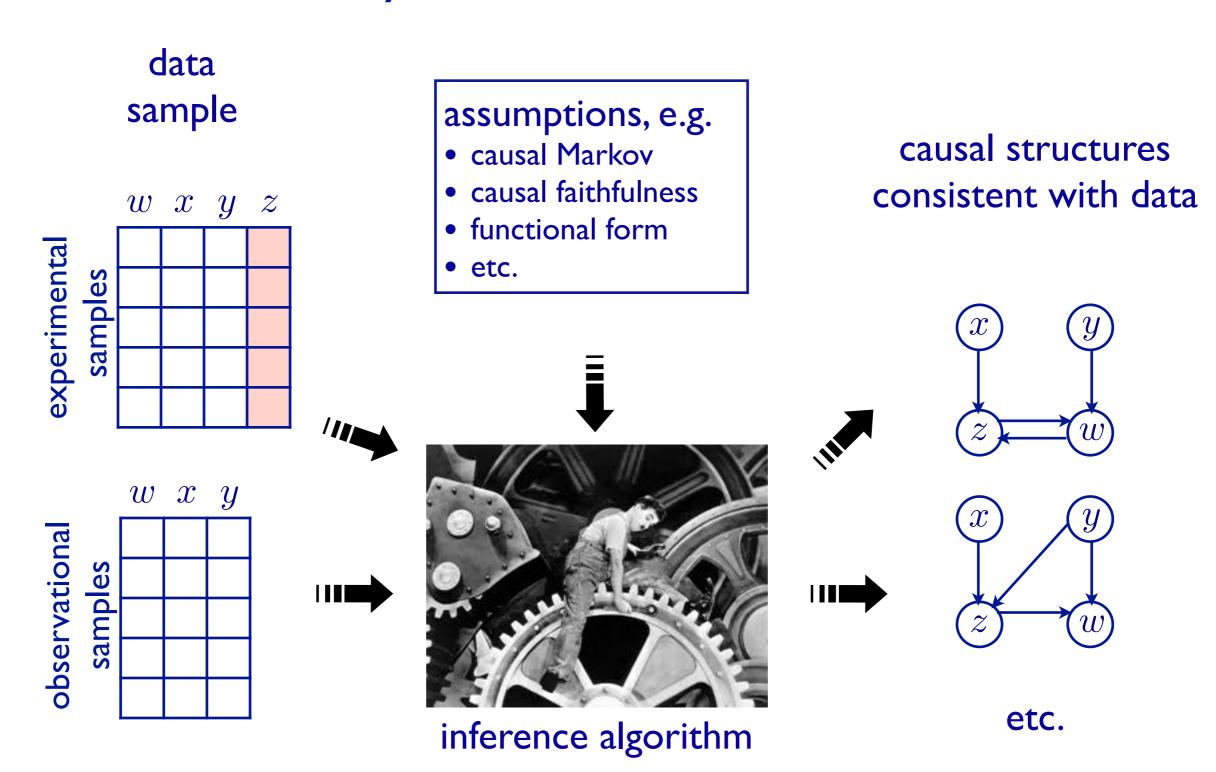


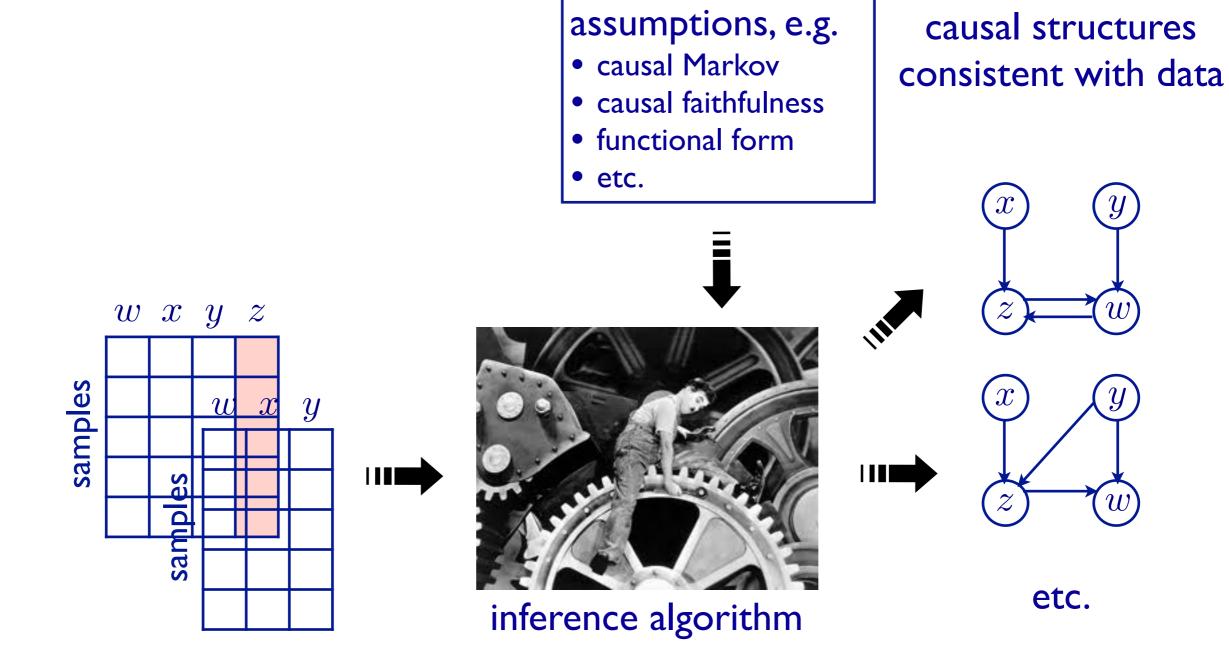
#### observational study



#### Combining Experiment and Observation





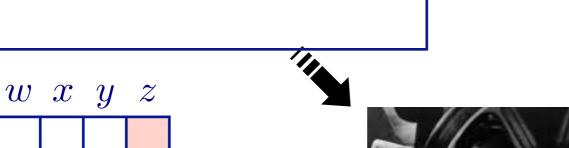


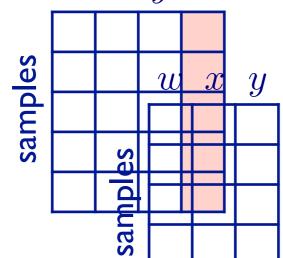
#### background knowledge

#### assumptions, e.g.

- causal Markov
- causal faithfulness
- functional form
- etc.

causal structures consistent with data

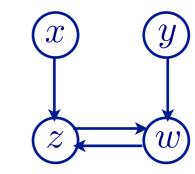


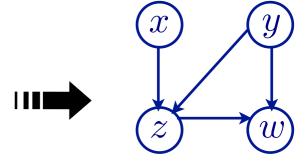






inference algorithm





etc.

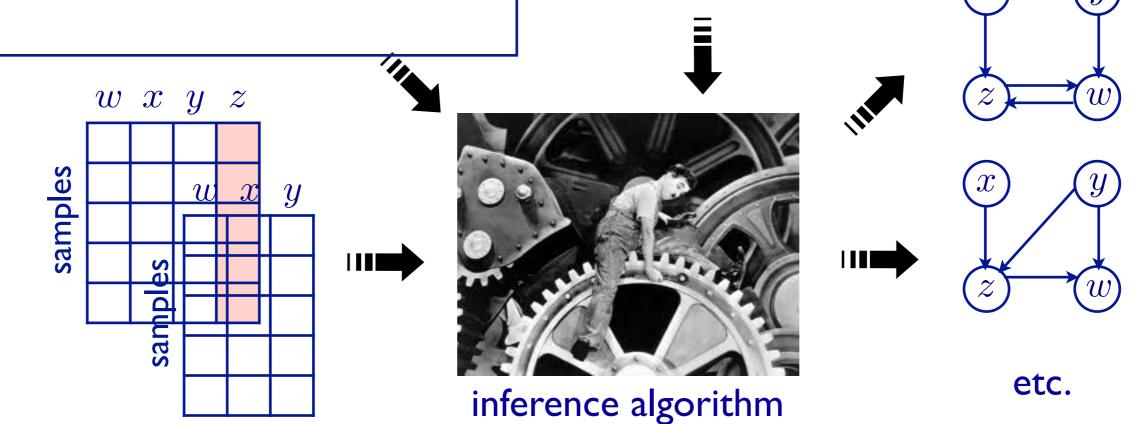
#### background knowledge

 edge presences/ absences

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causal structures consistent with data



#### background knowledge



samples

- edge presences/ absences
- pathways

#### assumptions, e.g.

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- functional form
- etc.

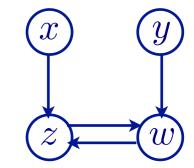
causal structures consistent with data

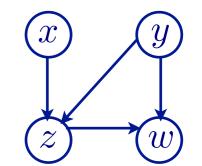




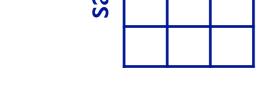






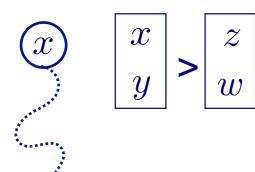


etc.



w x y z

#### background knowledge



- edge presences/ absences
- pathways
- tier orderings

#### assumptions, e.g.

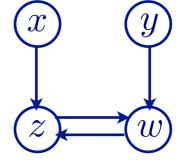
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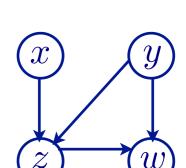




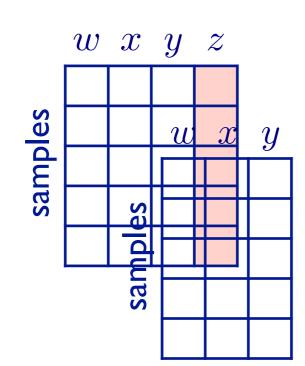


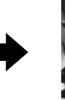






etc.



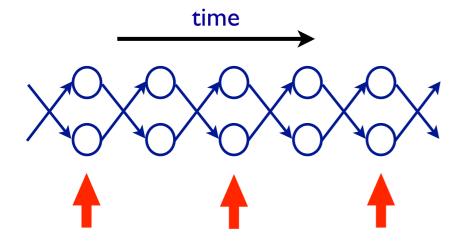






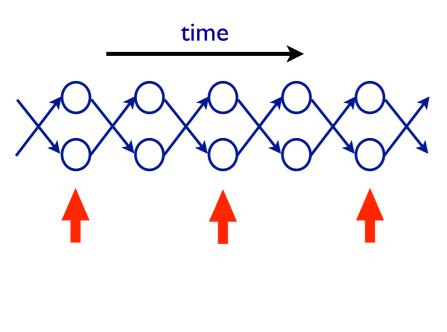
#### background knowledge $\boldsymbol{x}$ edge presences/ assumptions, e.g. causal structures absences • causal Markov consistent with data pathways • causal faithfulness • tier orderings • functional form • "priors" • etc. ${\boldsymbol{\mathcal{X}}}$ y zwsamples etc. inference algorithm

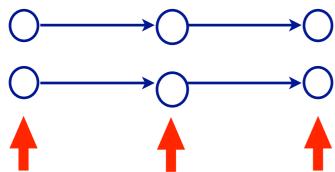
#### subsampled time series



(cf. work by Plis & Danks)

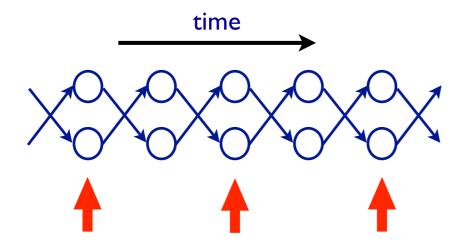
#### subsampled time series

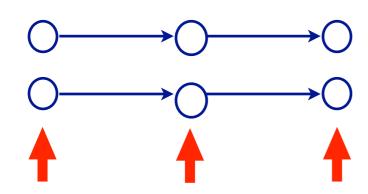




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#### subsampled time series





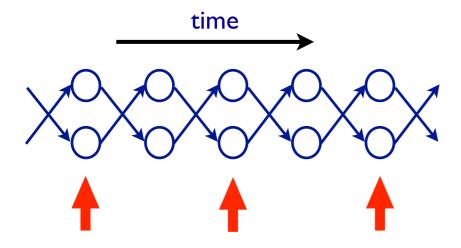
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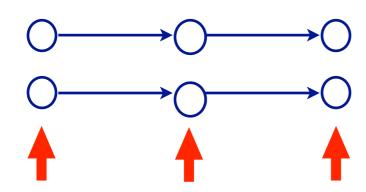




inference algorithm

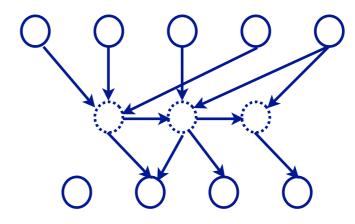
#### subsampled time series





(cf. work by Plis & Danks)

#### biological settings



(cf. work by Murray-Watters & Glymour)

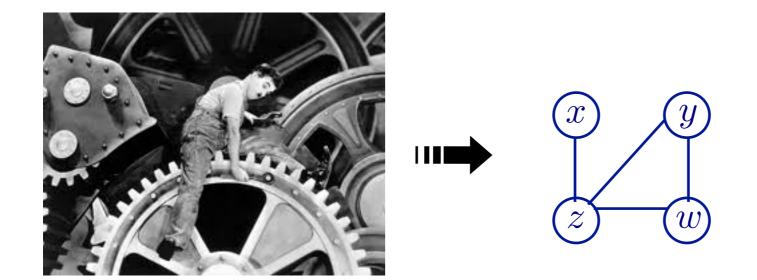




inference algorithm



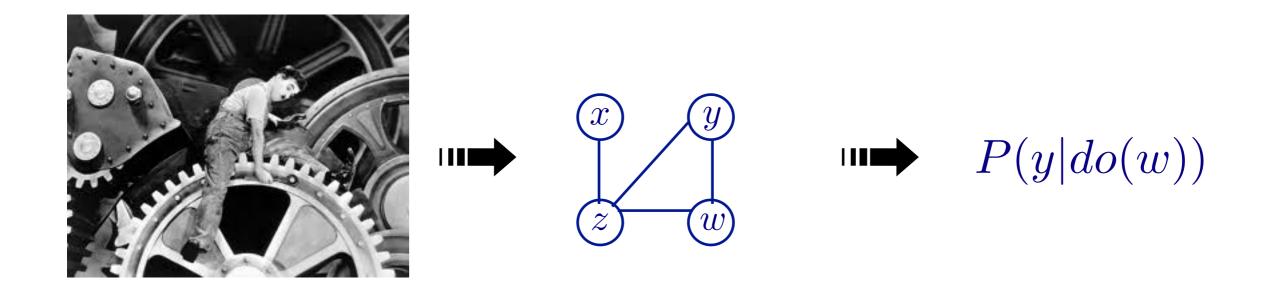
inference algorithm



inference algorithm

equivalence class

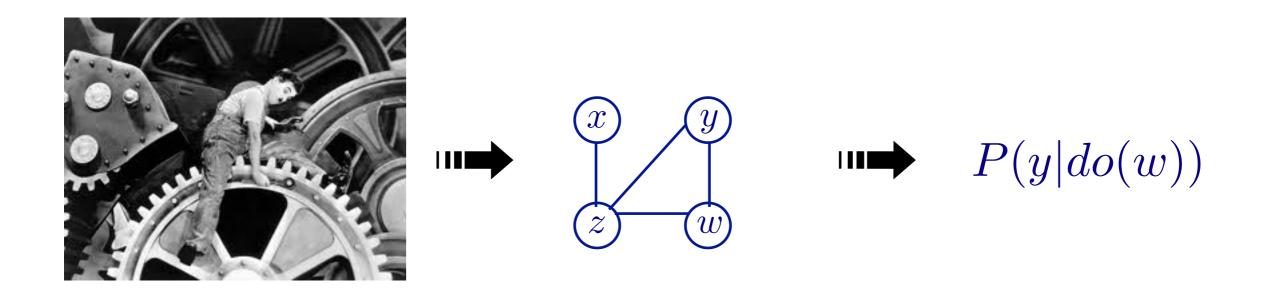
inference algorithm



equivalence class

causal effect

inference algorithm

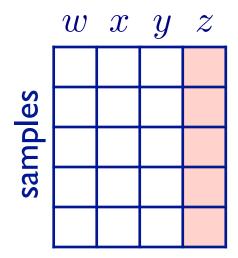


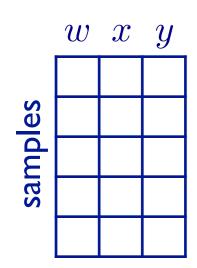
How to apply the do-calculus in settings when the causal structure is underdetermined?

equivalence class

causal effect

# data sample

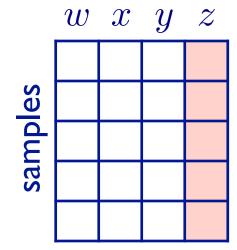


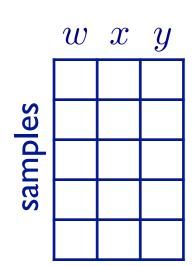


# data sample

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- etc.





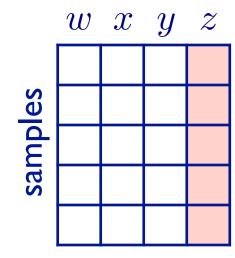
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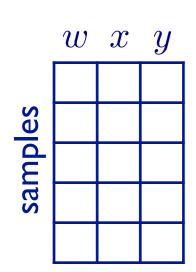
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#### background knowledge, e.g.

- pathways
- tier ordering
- "priors"
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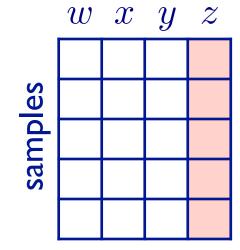
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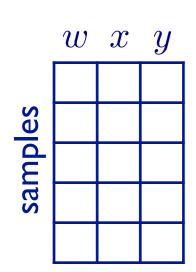
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#### setting

- subsampled time series
- tier structure





data sample

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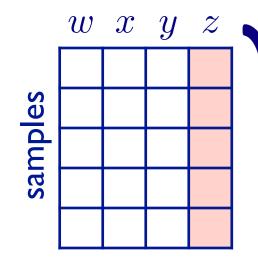
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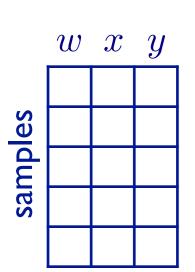
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(in)dependence constraints

$$x \not\perp \!\!\! \perp y |\mathbf{C}| |\mathbf{J}|$$

data sample

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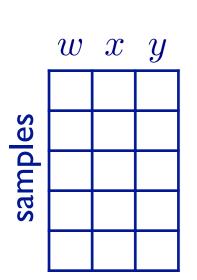
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- subsampled time series
- tier structure

w x y z



(in)dependence constraints

$$x \not\perp \!\!\! \perp y |\mathbf{C}| |\mathbf{J}|$$

Encode these as logical constraints on the underlying graph structure

# (max) SAT-solver

#### High-Level

data sample

w x

#### assumptions, e.g.

- causal Markov
- causal faithfulness
- etc.

#### background knowledge, e.g.

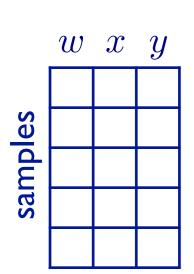
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samples

y



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Encode these as logical constraints on the underlying graph structure

#### d-separation and independence

• Under the assumption of causal Markov and causal Faithfulness:

$$x \not\perp y \mid \mathbf{C} \mid \mathbf{J} \iff x \not\perp y \mid \mathbf{C} \mid \mathbf{J}$$

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x and y are d-connected given C when variables in J are subject to intervention

x and y are dependent

given C when variables

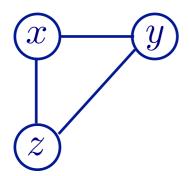
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$$x \perp \!\!\! \perp y$$

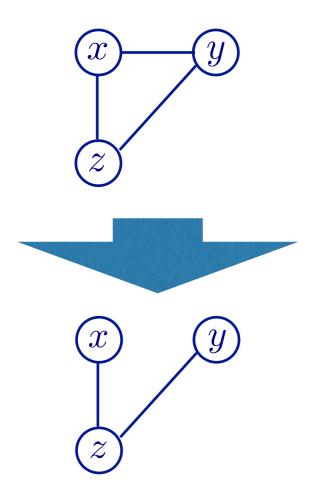
 $x \perp \!\!\!\perp y$ 

#### PC-algorithm



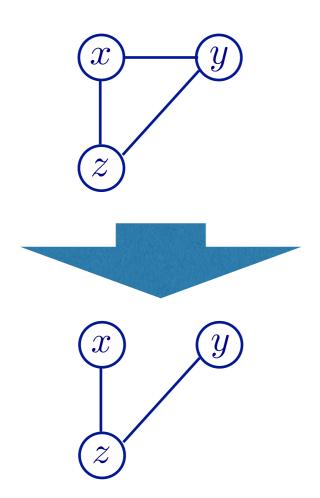
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## PC-algorithm



 $x \perp \!\!\!\perp y$ 

#### PC-algorithm

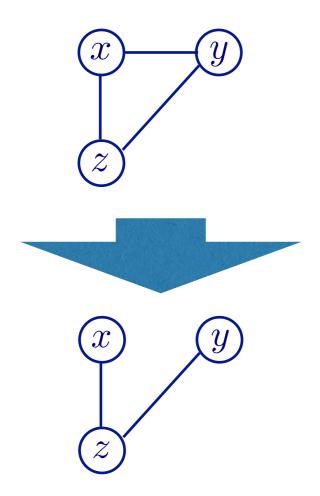


#### SAT-algorithm

define atoms 
$$\left\{ \begin{array}{l} A:=``x\to y\in G" \\ B:=``y\to x\in G" \\ C:=``z\to x\in G" \\ D:=``z\to y\in G" \\ \end{array} \right. ...$$

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encode 
$$\begin{cases} \neg A \land \neg B & \text{// direct edges} \\ \land \neg (C \land D) \text{// common causes} \\ \land \neg \dots & \text{// indirect paths} \end{cases}$$

 Formulate the independence constraints in propositional logic

$$x \perp \!\!\! \perp y \iff \neg A \land \neg B \dots$$
  
 $A = 'x \to y \text{ is present'}$ 

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$$\neg A \wedge \neg B \wedge \neg (C \wedge D) \wedge \neg \dots$$

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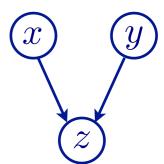
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 Find satisfying assignments using a SAT-solver

$$A = false$$
  $(x)$ 
 $B = false \iff$ 



 Formulate the independence constraints in propositional logic

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very general setting (allows for cycles and latents) and trivially complete

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$$B = false \iff (z)$$

- very general setting (allows for cycles and latents) and trivially complete
- **BUT**: erroneous test results induce conflicting constraints: UNsatisfiable

• Statistical independence tests produce errors

#### constraint

$$x \not\perp z$$

$$y \not\perp z$$

$$y \not\perp \!\!\! \perp z$$

$$x \perp \!\!\! \perp y$$

$$x \perp \!\!\! \perp y|z$$

- Statistical independence tests produce errors
  - Conflict: no graph can produce the set of constraints

#### constraint

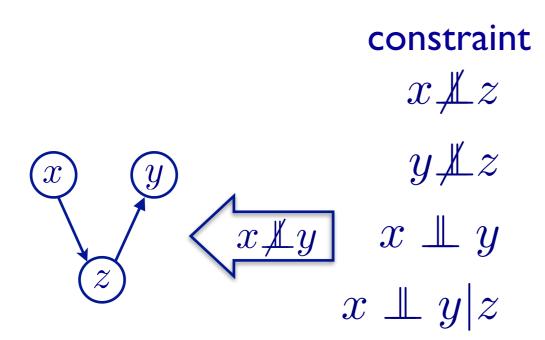
$$x \not\perp \!\!\! \perp z$$

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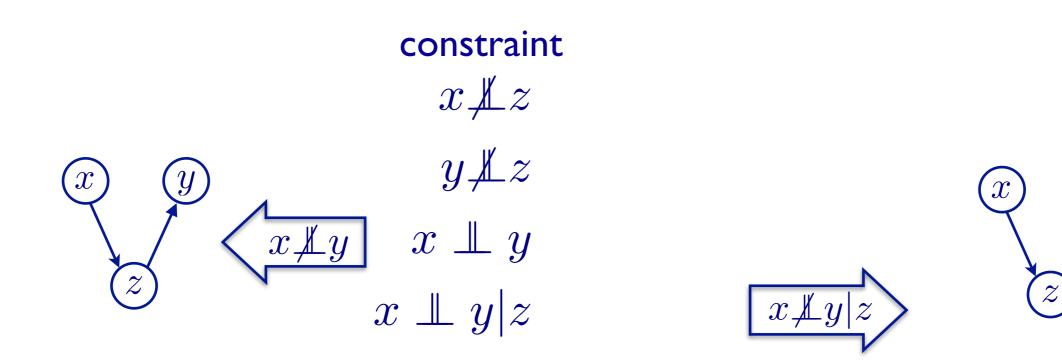
$$x \perp \!\!\! \perp y$$

$$x \perp \!\!\! \perp y|z$$

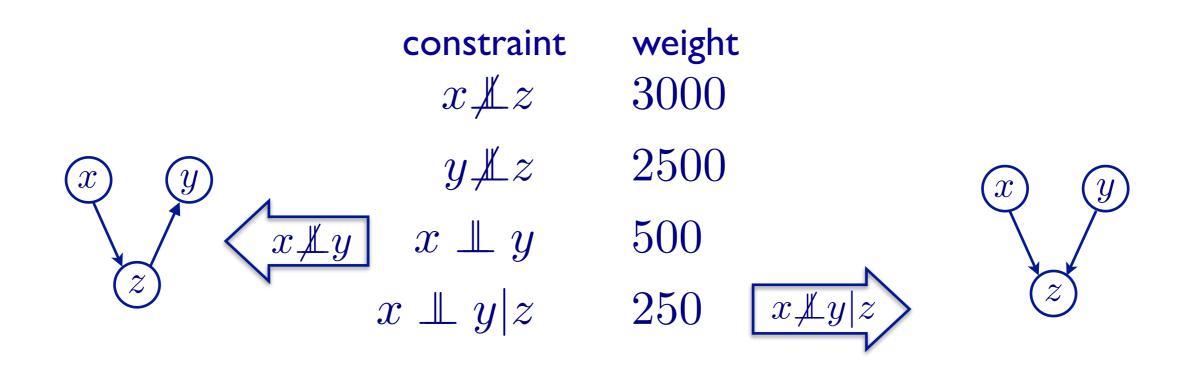
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#### Constraint Satisfaction Approach

 INPUT: (in)dependence constraints weighted according to reliability

$$\min_{G} \sum_{k \text{ : constraint } k \text{ is } \mathbf{not} \text{ satisfied by } G$$

• OUTPUT: a graph G that minimizes the cost

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What are suitable weights?

- Constant weights
  - unit weights for all constraint

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  - only treat rejections of the null-hypothesis as hard constraints, in line with classical statistics
  - give dependences infinite weight, maximize the independences (unit weight)
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- Log weights
  - obtain the probability of an (in)dependence and weigh it according to the log of the probability
  - Model selection with Bayes rule:

$$x \not\perp y|C$$
  $x \perp y|C$  VS.  $P(x|C)P(y|x,C)$   $P(x|C)P(y|C)$ 

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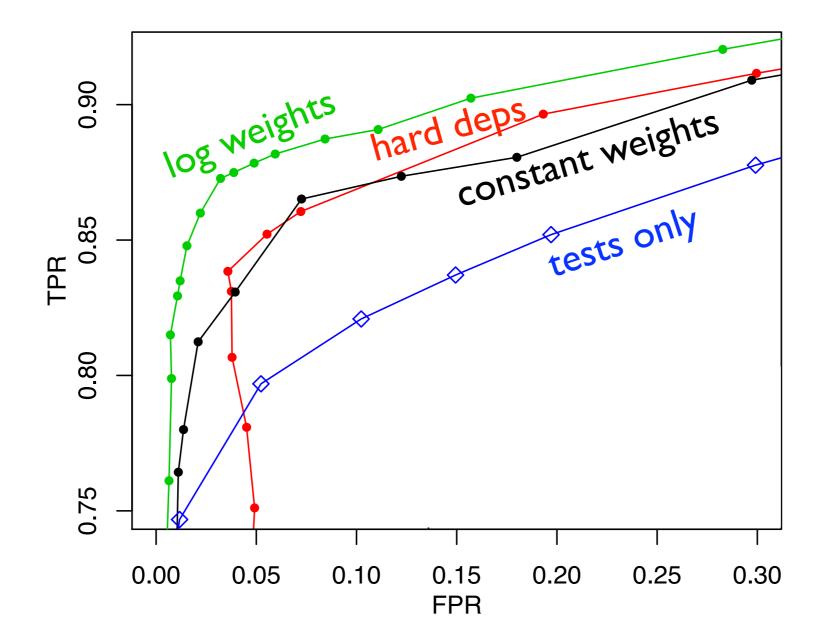
$$x \not\perp y|C$$
  $x \perp y|C$  VS.  $P(x|C)P(y|x,C)$   $P(x|C)P(y|C)$ 

 probabilistic classifier: find G such that if it were true, test results would be optimal in the sense of a proper score

#### **Optimization**

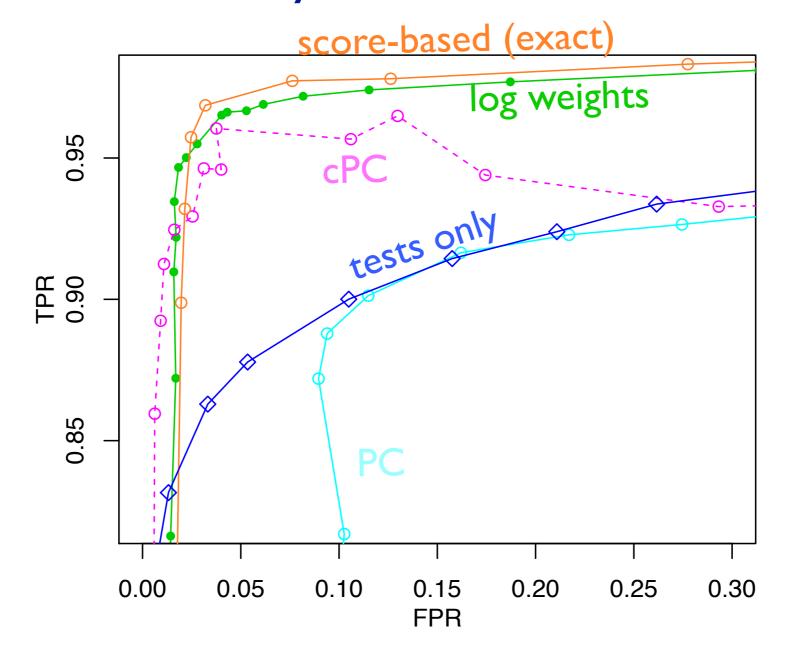
- Answer Set Programming (ASP) is a modern declarative programming paradigm
  - solver used: Clingo
  - SAT-solver and branch and bound algorithm
  - finds globally optimal weighted maxSAT solution

#### Simulation 1: cycles and latents



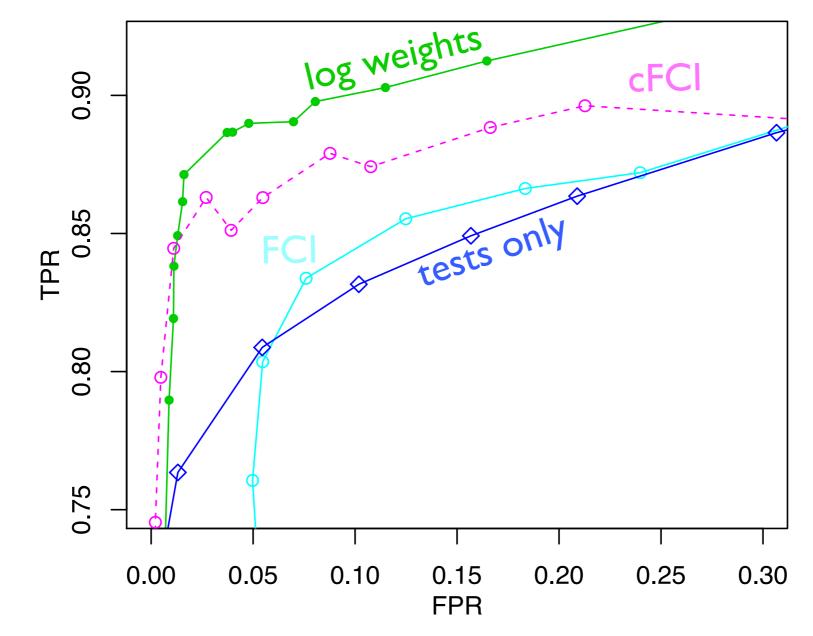
 ROC of dependences, passive observational data set, 6 observed variables, average degree 2; 500 samples, 200 models, linear Gaussian parameterization

#### Simulation 2: no cycles, no latents



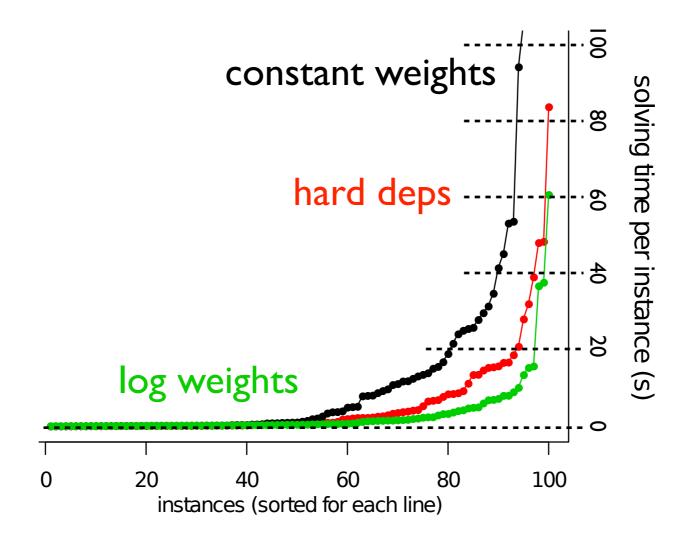
 cPC returns a fully determined output only 58/200 times at its optimum

## Simulation 3: no cycles, but latents



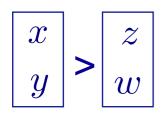
 cFCl only returns unambiguous results 61/200 times at its optimum

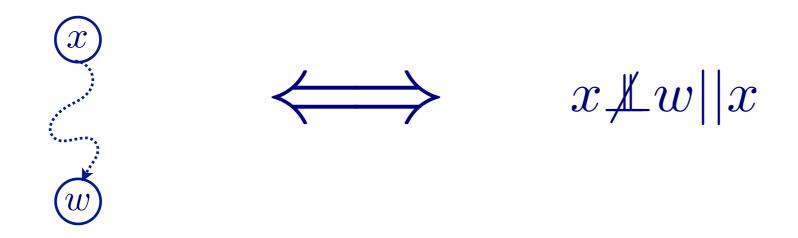
## Simulation 4: Scalability



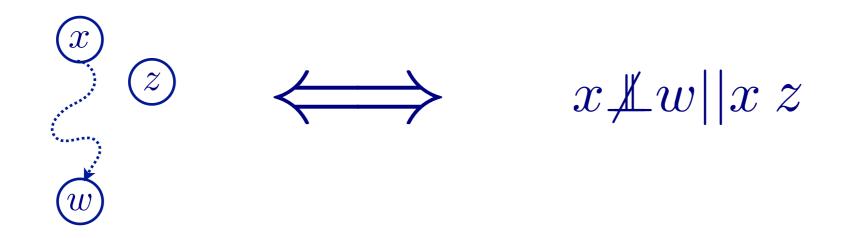
 up to 7 variables and only a few data sets for now (9x10^18 graphs)



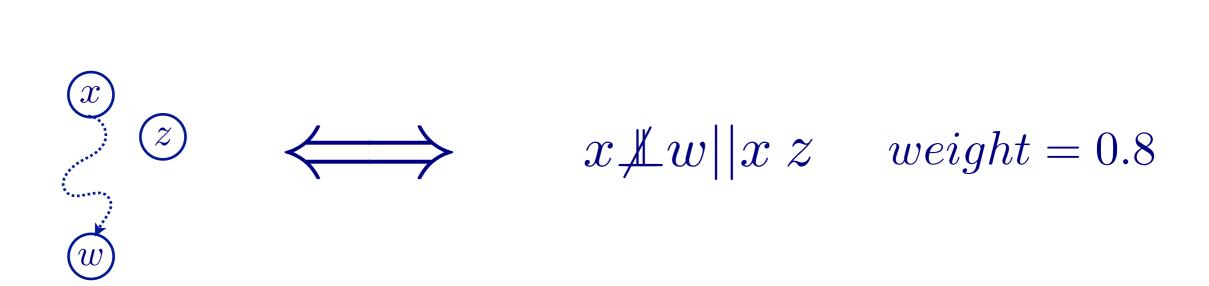




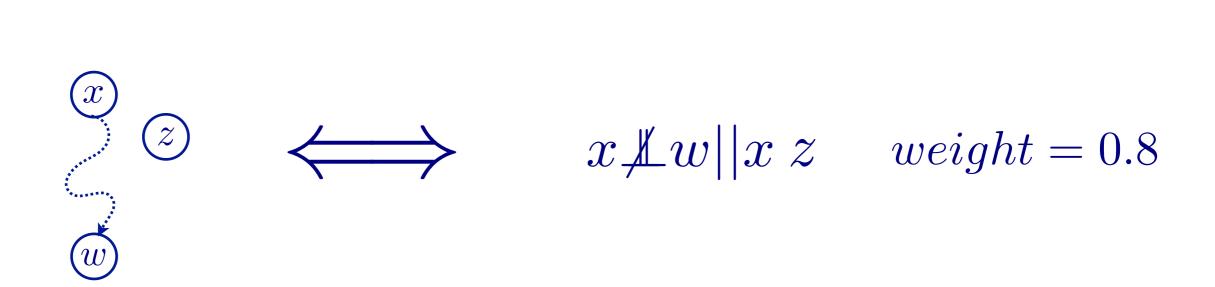
$$\begin{bmatrix} x \\ y \end{bmatrix} > \begin{bmatrix} z \\ w \end{bmatrix}$$



$$\begin{bmatrix} x \\ y \end{bmatrix} > \begin{bmatrix} z \\ w \end{bmatrix}$$

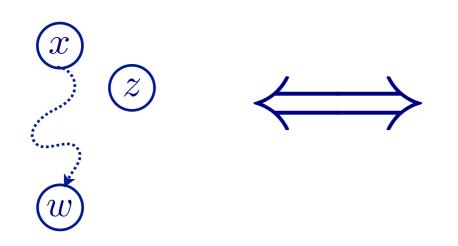


$$\begin{bmatrix} x \\ y \end{bmatrix} > \begin{bmatrix} z \\ w \end{bmatrix}$$



$$\begin{bmatrix} x \\ y \end{bmatrix} > \begin{bmatrix} z \\ w \end{bmatrix} \qquad \longleftrightarrow \qquad \begin{aligned} (x > z) \land (x > w) \\ \land (y > z \land (y > w)) \end{aligned}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} > \begin{bmatrix} z \\ w \end{bmatrix} \qquad \longleftrightarrow \qquad \begin{pmatrix} (x > z) \land (x > w) \\ \land (y > z \land (y > w)) \end{pmatrix}$$



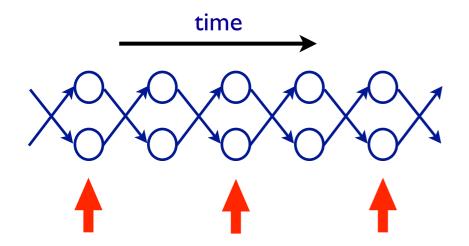
$$\iff x \not\perp w || x z \qquad weight = 0.8$$

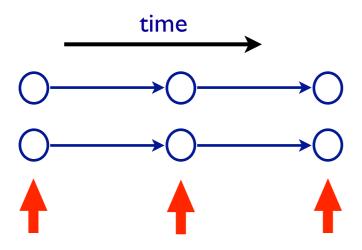
$$\begin{bmatrix} x \\ y \end{bmatrix} > \begin{bmatrix} z \\ w \end{bmatrix}$$

$$\iff \frac{(x > z) \land (x > w)}{\land (y > z \land (y > w)}$$

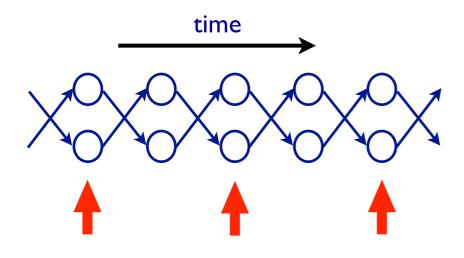
- specific probabilities for each graph
- soft sparsity constraint
- •

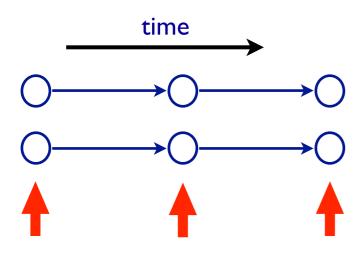
# Settings





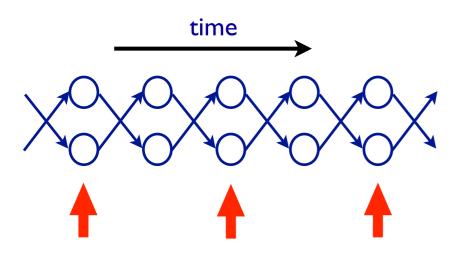
#### Settings

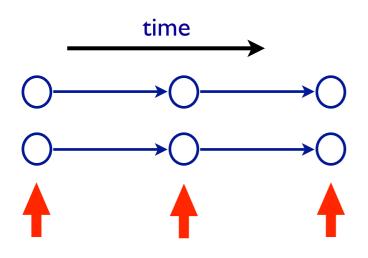




```
urange(1..5).
1 { u(U): urange(U) } 1.
\{ edge1(X,Y) \} :- node(X), node(Y).
path(X,Y,1) := edgel(X,Y).
path(X,Y,L) := path(X,Z,L-1), edgel(Z,Y),
L \ll U, u(U).
edgelu(X,Y) := path(X,Y,L), u(L).
conflu(X,Y) := path(Z,X,L), path(Z,Y,L),
node(X), node(Y), node(Z),
X < Y, L < U, u(U).
:- edgeu(X,Y), not edgelu(X,Y).
:- no edgeu(X,Y), edgelu(X,Y).
:- confu(X,Y), not conflu(X,Y).
:- no confu(X,Y), conflu(X,Y).
```

#### Settings





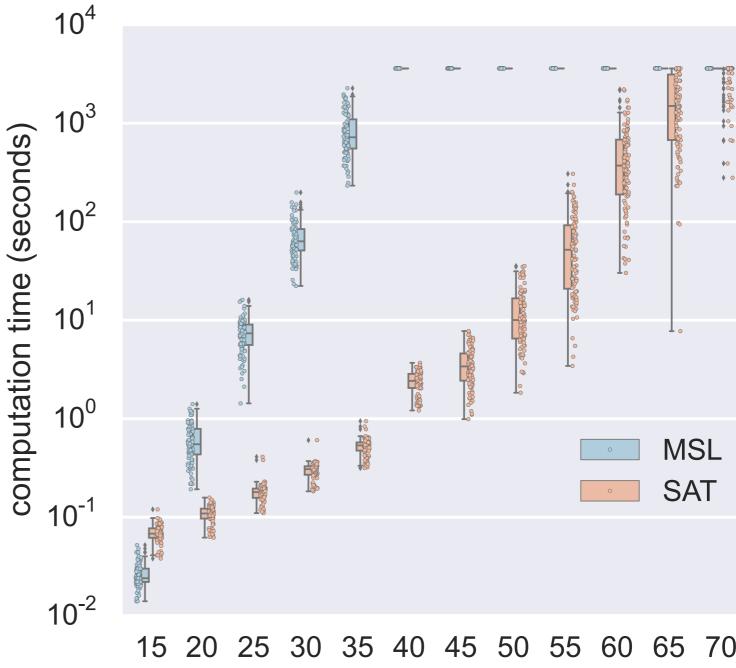
def. of how confounders arise due to subsampling

```
range for rate of subsampling
                   subsampling rate is unique
urange(1..5).
                            def. of edge in graph
1 { u(U): urange(U) } 1.
{ edge1(X,Y) } :- node(X), node(Y).
path(X,Y,1) := edgel(X,Y).
path(X,Y,L) := path(X,Z,L-1), edgel(Z,Y),
L \le U, u(U).
                          recursive def. of path
edgelu(X,Y) := path(X,Y,L), u(L).
                 def. of edge in subsampled graph
conflu(X,Y) := path(Z,X,L), path(Z,Y,L),
node(X),node(Y), node(Z),
X < Y, L < U, u(U).
:- edgeu(X,Y), not edgelu(X,Y).
:- no edgeu(X,Y), edgelu(X,Y).
:- confu(X,Y), not conflu(X,Y).
:- no confu(X,Y), conflu(X,Y).
         constraints on how edges in subsampled
```

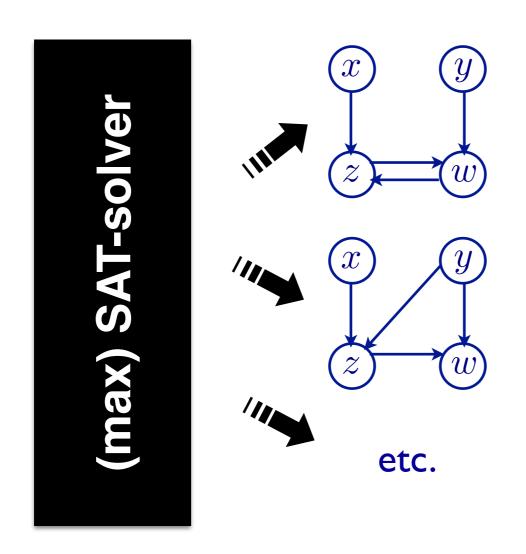
graph relate to edges in true graph

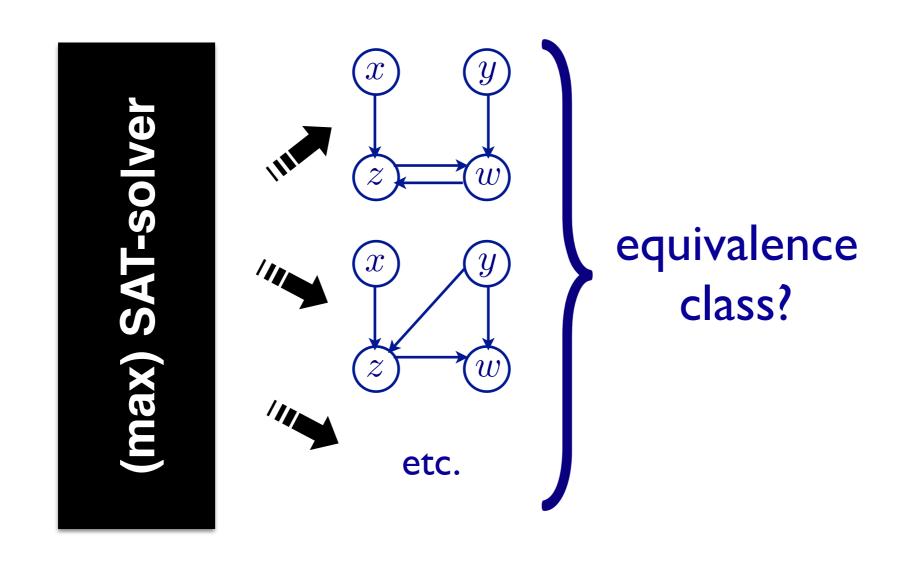
# Runtime comparison

For a graph determined at subsampling rate 2, infer the equivalence class of graphs at the system time scale (I-step)

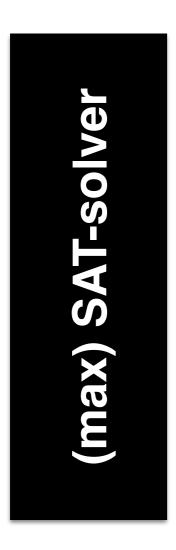


number of nodes in a graph





Query:





# (max) SAT-solver



# Query:

• list the structures in the equivalence class

(max) SAT-solver



# Query:

- list the structures in the equivalence class
- what structural features are determined?
  - edges, confounders
  - ancestral relations
  - pathways

# (max) SAT-solver



# Query:

- list the structures in the equivalence class
- what structural features are determined?
  - edges, confounders
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- what are the highest scoring equivalence classes?

# (max) SAT-solver





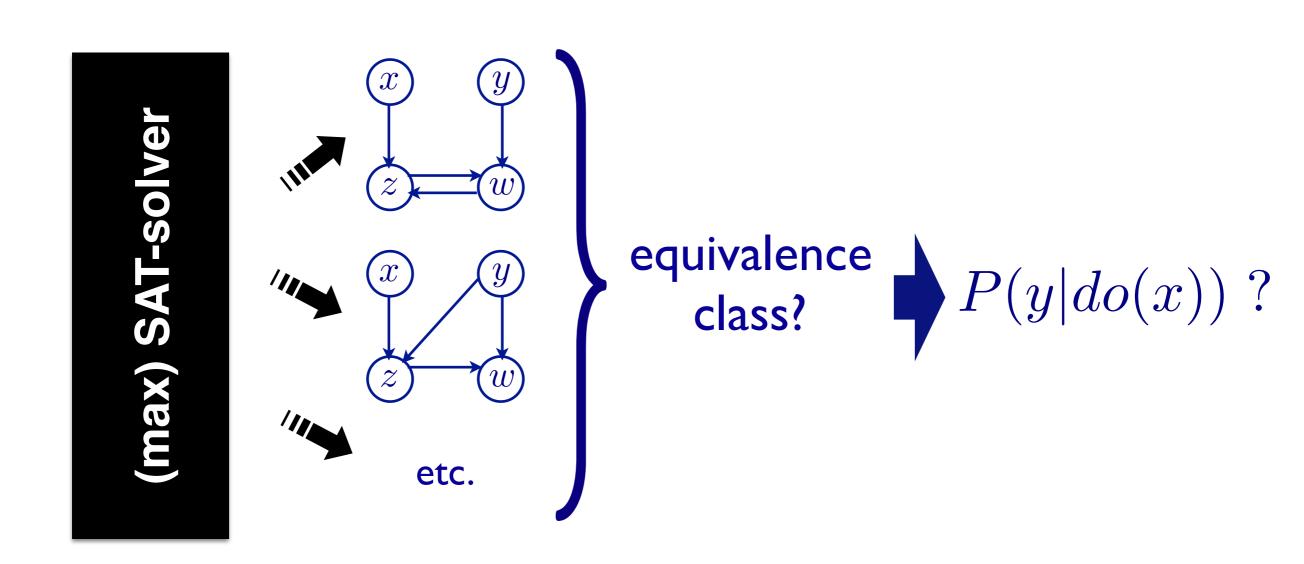
# Query:

- list the structures in the equivalence class
- what structural features are determined?
  - edges, confounders
  - ancestral relations
  - pathways
- what are the highest scoring equivalence classes?

# Response:

- enumeration of solutions
- "backbone" of the SAT-instance
- •

# Computing Causal Effects



equivalence 
$$P(y|do(x))$$
?

equivalence 
$$P(y|do(x))$$
?

• enumerate each graph in the equivalence class and run the Tian-Shpitser algorithm to determine the causal effect?

- enumerate each graph in the equivalence class and run the Tian-Shpitser algorithm to determine the causal effect?
- Alternative:

- enumerate each graph in the equivalence class and run the Tian-Shpitser algorithm to determine the causal effect?
- Alternative:

### do-calculus

Rule I (insertion/deletion of observations)

$$P(y|do(x), z, w) = P(y|do(x), w)$$
 if  $Y \perp \!\!\! \perp Z|X, W||X$ 

Rule 2 (action/observation exchange)

$$P(y|do(x), do(z), w) = P(y|do(x), z, w)$$
 if  $Y \perp I_Z|X, Z, W|X$ 

Rule 3 (insertion/deletion of actions)

$$P(y|do(x), do(z), w) = P(y|do(x), w)$$
 if  $Y \perp I_Z|X, W|X$ 

- enumerate each graph in the equivalence class and run the Tian-Shpitser algorithm to determine the causal effect?
- Alternative:

## do-calculus

Rule I (insertion/deletion of observations)

$$P(y|do(x), z, w) = P(y|do(x), w) \text{ if } Y \perp Z|X, W||X|$$

Rule 2 (action/observation exchange)

$$P(y|do(x), do(z), w) = P(y|do(x), z, w)$$
 if  $Y \perp I_Z|X, Z, W|X$ 

Rule 3 (insertion/deletion of actions)

$$P(y|do(x), do(z), w) = P(y|do(x), w)$$
 if  $Y \perp I_Z|X, W||X|$ 

- enumerate each graph in the equivalence class and run the Tian-Shpitser algorithm to determine the causal effect?
- Alternative:

### do-calculus

Rule I (insertion/deletion of observations)

$$P(y|do(x), z, w) = P(y|do(x), w) \text{ if } Y \perp Z|X, W||X|$$

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$$P(y|do(x), do(z), w) = P(y|do(x), z, w)$$
 if  $Y \perp I_Z|X, Z, W|X$ 

Rule 3 (insertion/deletion of actions)

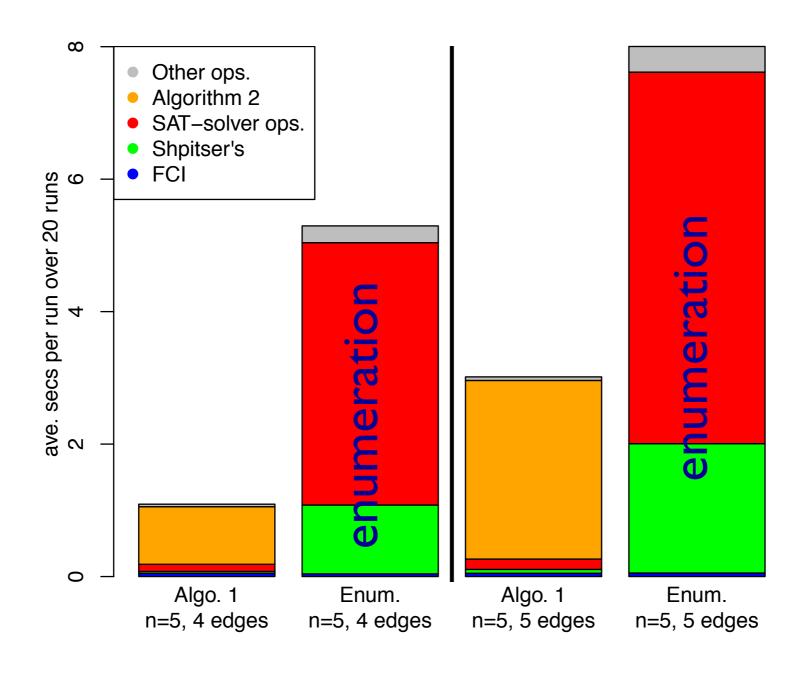
$$P(y|do(x), do(z), w) = P(y|do(x), w) \text{ if } Y \perp I_Z|X, W||X$$

search in the equivalence class over the possible applications of the do-calculus rules by querying the satisfaction of their conditions

# Algorithm for the do-calculus when the graph is unknown

- determine the equivalence class implicitly using a SAT-solver
- query one solution graph G
- run the Tian-Shpitser-algorithm on G to determine whether the causal effect P(y|do(w)) is determined for G
- if it is, determine which do-calculus rules were applied and record the constraints  $C_1, \ldots, C_n$  that were used
  - add  $\neg C_1 \lor \ldots \lor \neg C_n$  as a constraint to refine the current equivalence class
- if not, determine the "hedge" H and add  $\neg H$  to refine the current equivalence class
- repeat until the equivalence is exhausted
- return the set of estimates of the causal effect and NA if it cannot be determined in one member of the equivalence class

# Comparison of our approach to enumeration



# In sum: do-calculus using a SAT-solver

• enables computation of the causal effect when the graph structure is underdetermined

# In sum: do-calculus using a SAT-solver

- enables computation of the causal effect when the graph structure is underdetermined
- how should one estimate a causal effect when the equivalence class of causal structures was determined on the basis of a set of conflicted constraints?

# In sum: do-calculus using a SAT-solver

- enables computation of the causal effect when the graph structure is underdetermined
- how should one estimate a causal effect when the equivalence class of causal structures was determined on the basis of a set of conflicted constraints?
- some avenues one can explore with the query-based approach:
  - explore more closely the conditions involved in determining the causal effect
  - find multiple different estimators
  - even though the overall graph structure may not be determinable without resolving conflicts, some causal effects may be

## Conclusion

- the use of general purpose SAT-solvers provides an extraordinarily versatile tool for causal discovery
- it opens new avenues for handling background knowledge and the computation of causal effects when the causal structure is underdetermined
- it provides a query based approach in contrast to a representation of an equivalence class of causal structures
- it suggests that current general purpose constraint solvers outperform domain specific approaches

## References

- Hyttinen, Eberhardt & Järvisalo (2015). Do-calculus when the true graph is unknown. UAI 2015.
- Hyttinen, Eberhardt & Järvisalo (2014). Constraint-based Causal Discovery: Conflict Resolution with Answer Set Programming. UAI 2014.
- Hyttinen, Hoyer, Eberhardt & Järvisalo (2013). Discovering Cyclic Causal Models with Latent Variables: A General SAT-Based Procedure. UAI 2013.
- {Hyttinen, Plis, Danks, Eberhardt & Järvisalo} (work in progress). Causal Discovery from Subsampled Time Series Data by Constraint Optimization.

### Other relevant work that is closely related:

- Triantafillou & Tsamardinos (2015). Constraint-based Causal Discovery from Multiple Interventions Over Overlapping Variable Sets. JMLR 16(Nov):2147–2205.
- Claassen & Heskes (2011). A logical characterization of constraint-based causal discovery. UAI 2011.
- Triantafillou, Tsamardinos & Tollis (2010). Learning Causal Structure from Overlapping Variable Sets. AISTATS 2010.

Thank you!